

E9:261

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Recap ...

- **Dynamic programming**
 - **solving an optimal search with sub-paths being optimal**
- **Dynamic Time Warping**
 - **Constraints on the path**
 - **end-point constraints**
 - **monotonicity constraints**
 - **local constraints**
 - **global constraints**
 - **slope weighting**
- **DTW recursive solution**

Local constraints in DTW

TABLE 4.5. Summary of sets of local constraints and the resulting path specifications

Type	Diagram	Allowable Path Specification
I		$\mathcal{P}_1 \rightarrow (1, 0)$ $\mathcal{P}_2 \rightarrow (1, 1)$ $\mathcal{P}_3 \rightarrow (0, 1)$
II		$\mathcal{P}_1 \rightarrow (1, 1)(1, 0)$ $\mathcal{P}_2 \rightarrow (1, 1)$ $\mathcal{P}_3 \rightarrow (1, 1)(0, 1)$
III		$\mathcal{P}_1 \rightarrow (2, 1)$ $\mathcal{P}_2 \rightarrow (1, 1)$ $\mathcal{P}_3 \rightarrow (1, 2)$
IV		$\mathcal{P}_1 \rightarrow (1, 1)(1, 0)$ $\mathcal{P}_2 \rightarrow (1, 2)(1, 0)$ $\mathcal{P}_3 \rightarrow (1, 1)$ $\mathcal{P}_4 \rightarrow (1, 2)$
V		$\mathcal{P}_1 \rightarrow (1, 1)(1, 0)(1, 0)$ $\mathcal{P}_2 \rightarrow (1, 1)(1, 0)$ $\mathcal{P}_3 \rightarrow (1, 1)$ $\mathcal{P}_4 \rightarrow (1, 1)(0, 1)$ $\mathcal{P}_5 \rightarrow (1, 1)(0, 1)(0, 1)$
VI		$\mathcal{P}_1 \rightarrow (1, 1)(1, 1)(1, 0)$ $\mathcal{P}_2 \rightarrow (1, 1)$ $\mathcal{P}_3 \rightarrow (1, 1)(1, 1)(0, 1)$
VII		$\mathcal{P}_1 \rightarrow (1, 1)(1, 0)(1, 0)$ $\mathcal{P}_2 \rightarrow (1, 2)(1, 0)(1, 0)$ $\mathcal{P}_3 \rightarrow (1, 3)(1, 0)(1, 0)$ $\mathcal{P}_4 \rightarrow (1, 1)(1, 0)$ $\mathcal{P}_5 \rightarrow (1, 2)(1, 0)$ $\mathcal{P}_6 \rightarrow (1, 3)(1, 0)$ $\mathcal{P}_7 \rightarrow (1, 1)$ $\mathcal{P}_8 \rightarrow (1, 2)$ $\mathcal{P}_9 \rightarrow (1, 3)$

DTW Solution

1. Initialization

$$D_A(1, 1) = d(1, 1)m(1).$$

2. Recursion

For $1 \leq i_x \leq T_x$, $1 \leq i_y \leq T_y$ such that i_x and i_y stay within the allowable grid, compute

$$D_A(i_x, i_y) = \min_{(i'_x, i'_y)} [D_A(i'_x, i'_y) + \zeta((i'_x, i'_y), (i_x, i_y))],$$

where $\zeta((i'_x, i'_y), (i_x, i_y))$ is defined by Eq. (4.162).

3. Termination

$$d(\mathcal{X}, \mathcal{Y}) = \frac{D_A(T_x, T_y)}{M_\phi}.$$

$$\zeta((i'_x, i'_y), (i_x, i_y)) = \sum_{\ell=0}^{L_s} d(\phi_x(T' - \ell), \phi_y(T' - \ell))m(T' - \ell)$$

Disadvantages of DTW

- **Based on heuristics**
- **Creating templates from large number of examples can be hard.**
- **With large vocabulary sizes, computationally intractable.**
- **Not a statistical method.**